

Large Sample Theory of Penalized Splines

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Main Results

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Spline Models

Penalized
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Zero-degree
Splines – 1st
order penalty

Zero-degree
Splines – 2nd
order penalty

Linear Splines

Higher order
penalties –
some results

Conclusions

- P-spline estimators are approximately binned Nadaraya-Watson kernel estimators
- The number of knots is not important, provided it is grows fast enough (**confirms folklore**)
- The degree of the spline does not affect the rate of convergence (**surprising to me**)
- Order of equivalent kernel and rate of convergence of estimator depend on the order of the penalty

Univariate nonparametric regression

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Conclusions

- Assume a univariate nonparametric model

$$y_i = f(x_i) + \epsilon_i, \quad i = 1, \dots, n$$

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Conclusions

- A spline is a piecewise polynomial
 - its polynomial form changes at “knots”
 - $p - 1$ derivatives are continuous at knots
 - p th derivative jumps at knots
 - nonparametric if the knots become dense

Three methods of spline fitting

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Conclusions

- Regression splines
 - fit by ordinary (unweighted) least squares
- Smoothing splines
 - knot at each unique value of x
 - excessive number of knots can be a problem with more complex models
- Penalized splines
 - knots, degree, and penalty chosen independently

Why Penalized Splines Have Become Popular

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Conclusions

- Reasonably easy to understand
- Work well in practice
- Combines nicely with parametric models to form semiparametric models, e.g., the partially linear model

$$y_i = m(x_i) + \beta^T \mathbf{z}_i + \epsilon_i$$

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Conclusions

- Can be fit using **parametric** statistical software
 - by MCMC using, say, WinBUGS
 - by mixed model software
 - using Matt Wand's "SemiPar" package in R (a front-end to R's mixed model software)
 - for generalized regression by GLMM software

B-splines

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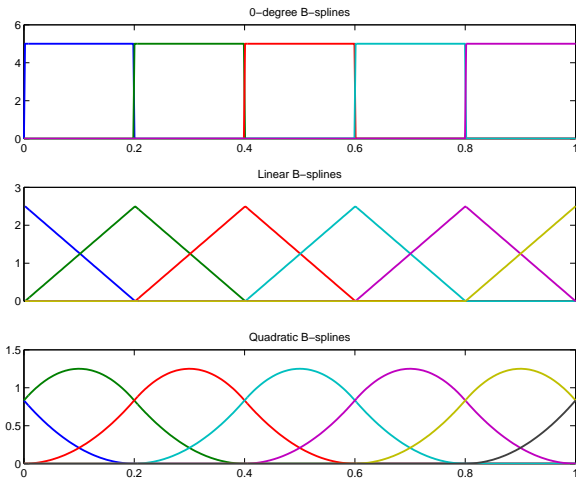
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p -degree spline model

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- The model:

$$f(x) = \sum_{k=1}^{K+p} b_k B_k(x), \quad x \in (0, 1)$$

- p th degree B-spline basis:

$$\{B_k : k = 1, \dots, K + p\}$$

- knots:

$$\kappa_0 = 0 < \kappa_1 < \dots < \kappa_K = 1$$

Penalized least-squares

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- Penalized least-squares minimizes

$$\sum_{i=1}^n \left\{ y_i - \sum_{k=1}^{K+p} \hat{b}_k B_i(x_i) \right\}^2 + \lambda \sum_{k=m+1}^{K+p} \{ \Delta^m(\hat{b}_k) \}^2,$$

- $\Delta b_k = b_k - b_{k-1}$ and $\Delta^m = \Delta(\Delta^{m-1})$
 - $\Delta = 1 \Rightarrow$ constant functions are unpenalized
 - $\Delta = 2 \Rightarrow$ linear functions are unpenalized

$$p = 0, m = 1$$

Assume:

- $x_1 = 1/n, x_2 = 2/n, \dots, x_n = 1$
- $\kappa_0 = 0, \kappa_1 = 1/K, \kappa_2 = 2/K, \dots, \kappa_K = 1$

$$p = 0, m = 1$$

Assume:

- $x_1 = 1/n, x_2 = 2/n, \dots, x_n = 1$
- $\kappa_0 = 0, \kappa_1 = 1/K, \kappa_2 = 2/K, \dots, \kappa_K = 1$
- $B_k(x) = I\{\kappa_{k-1} < x \leq \kappa_k\}, 1 \leq k \leq K$

$$p = 0, \quad m = 1$$

Assume:

- $x_1 = 1/n, x_2 = 2/n, \dots, x_n = 1$
- $\kappa_0 = 0, \kappa_1 = 1/K, \kappa_2 = 2/K, \dots, \kappa_K = 1$
- $B_k(x) = I\{\kappa_{k-1} < x \leq \kappa_k\}, 1 \leq k \leq K$
- assume that n/K is an integer

$$p = 0, \quad m = 1$$

Assume:

- $x_1 = 1/n, x_2 = 2/n, \dots, x_n = 1$
- $\kappa_0 = 0, \kappa_1 = 1/K, \kappa_2 = 2/K, \dots, \kappa_K = 1$
- $B_k(x) = I\{\kappa_{k-1} < x \leq \kappa_k\}, 1 \leq k \leq K$
- assume that n/K is an integer
- then $X^T X = MI_K$ where I_K

$p = 0, m = 1$, continued

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Assume further:

- $m = 1$

Then

$$D^T D = \begin{pmatrix} 1 & -1 & 0 & \cdots & 0 & 0 \\ -1 & 2 & -1 & \cdots & 0 & 0 \\ 0 & -1 & 2 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 2 & -1 \\ 0 & 0 & 0 & \cdots & -1 & 1 \end{pmatrix},$$

$p = 0, m = 1$, PLS estimator

The PLS estimator solves:

$$\Lambda \hat{\mathbf{b}} = \mathbf{z} = \bar{\mathbf{y}} / (1 + 2\lambda)$$

where

$$\Lambda = \begin{pmatrix} \theta & \eta & 0 & 0 & \cdots & 0 & 0 \\ \eta & 1 & \eta & 0 & \cdots & 0 & 0 \\ 0 & \eta & 1 & \eta & \cdots & 0 & 0 \\ 0 & 0 & \eta & 1 & \cdots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \cdots & 1 & \eta \\ 0 & 0 & 0 & 0 & \cdots & \eta & \theta \end{pmatrix}, \quad \eta = -\frac{\lambda}{1 + 2\lambda}$$

Let $\rho \in (0, 1)$ be a root of

$$\eta + \rho + \eta\rho^2 = 0.$$

Then

$$\rho = \frac{1 - \sqrt{1 - 4\eta^2}}{-2\eta} = \frac{1 + 2\lambda - \sqrt{1 + 4\lambda}}{2\lambda}.$$

Define

$$T_i = (\rho^{i-1}, \rho^{i-2}, \dots, \rho, 1, \rho, \rho^2, \dots, \rho^{K-i})^T$$

T_i is orthogonal to all columns of Λ except the first, last, and i th

Finite-sample kernel

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Finite-sample kernel:

$$\hat{f}(x) = \sum_{j=1}^K H(x, \bar{x}_j) \bar{y}_j$$

Three kernels corresponding to first-order penalty

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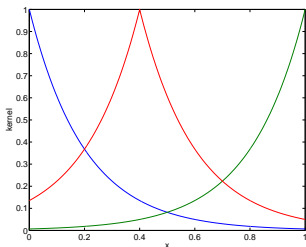
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Conclusions



- x is an “estimation point” (here fixed at 0.4)

- finite-sample kernel is linear combination of three kernels
- double exponential kernel centered at x
- boundary kernels are $\exp(-x)$ and $\exp(x)$
- weights for the boundary kernels are asymptotically negligible
- all kernels can be re-scaled by a bandwidth

Finite-sample kernels, first-order penalty

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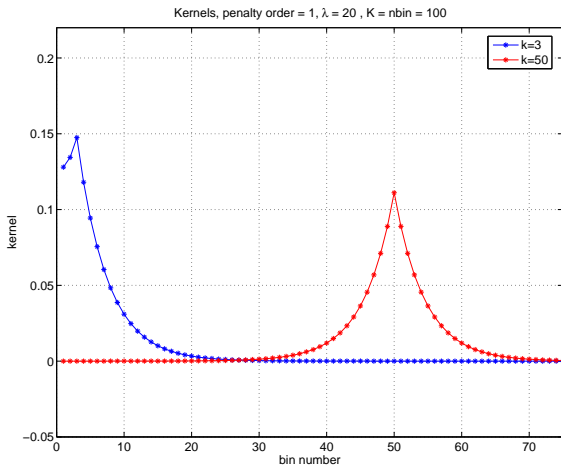
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Connection with smoothing splines

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We get the same equivalent kernel as for smoothing splines with a penalty on the first derivative

Finding \widehat{b}_i – interior case

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Conclusions

- Suppose $i/K \rightarrow x \in (0, 1)$ (non-boundary case)
- After some algebra:

$$\widehat{b}_i \sim \frac{\sum_{j=1}^K \rho^{|i-j|} \bar{y}_j}{\sum_{j=1}^K \rho^{|i-j|}}.$$

- Note that

$$\widehat{f}(x) = \widehat{b}_i$$

for x in the i th bin

Equivalence to N-W kernel estimator

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Conclusions

- After some more algebra

$$\rho^{|i-j|} \sim \exp \left\{ -\frac{|\bar{x}_i - \bar{x}_j|}{hn^{-1/5}} \right\}$$

- Thus, \hat{f}_n is asymptotically equivalent to the Nadaraya-Watson estimator with
 - double exponential kernel $H(x) = (1/2) \exp(-|x|)$
 - bandwidth $hn^{-1/5}$

Nadaraya-Watson kernel estimators

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Model:

$$y_i = f(x_i) + \epsilon_i$$

Nadaraya-Watson estimator:

$$\hat{f}(x) = \frac{\sum_{i=1}^n H\{(x_i - x)/h_n\} y_i}{\sum_{i=1}^n H\{(x_i - x)/h_n\}}$$

- $H(\cdot)$ is called the **kernel function**
- h_n is the **bandwidth**

Binned Nadaraya-Watson kernel estimators

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Binned Nadaraya-Watson estimator:

- range of the x_i divided into K subintervals (bins)
- \bar{x}_j is average of x_i in i th bin
- \bar{y}_j is average of y_i such that x_i is in the i th bin

$$\hat{f}(x) = \frac{\sum_{j=1}^K H\{(\bar{x}_j - x)/h_n\} \bar{y}_j}{\sum_{j=1}^K H\{(\bar{x}_j - x)/h_n\}}$$

P-spline equivalent to a Nadaraya-Watson kernel estimator

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- Thus, \hat{f}_n is asymptotically equivalent to a binned Nadaraya-Watson estimator with
 - double exponential kernel $H(x) = (1/2) \exp(-|x|)$
 - bandwidth $hn^{-1/5}$
- binned bias is negligible if $K = Cn^\gamma$ for $\gamma > 2/5$ and $C > 0$
- “negligible” means $o(n^{-2/5})$

Selecting λ to achieve desired bandwidth

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Conclusions

- To get bandwidth $hn^{-1/5}$ we need λ chosen as

$$\lambda \sim \{(Cn^\gamma)(hn^{-1/5})\}^2 = (\# \text{ knots} \times \text{bandwidth})^2$$

Asymptotic Distribution

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Conclusions

For $x \in (0, 1)$, as $n \rightarrow \infty$ we have

$$n^{2/5} \{ \hat{f}_n(x) - f(x) \} \Rightarrow N\{ \mathcal{B}(x), \mathcal{V}(x) \}$$

where

- $\mathcal{B}(x) = h^2 f^{(2)}(x)$
- $\mathcal{V}(x) = 2^{-1} h^{-1} \sigma^2(x)$

Some folklore

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Conclusions

- **Folklore:** The number of knots is not important, provided that it is large enough.

- **Confirmation:**

$$K \sim Cn^\gamma \text{ with } C > 0 \text{ and } \gamma > 2/5. \quad (1)$$

- **Folklore:** The value of the penalty parameter is crucial.

- **Confirmation:**

$$\lambda \sim C^2 h^2 n^{2\gamma-2/5} = (\# \text{ knots} \times \text{bandwidth})^2 \quad (2)$$

for some $h > 0$.

- **Folklore:** Modeling bias is small.
 - **Confirmation:** Modeling bias does not appear in asymptotic bias provided (1) and (2) hold.

Order of a kernel and bias

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Conclusions

Moments: k th moment is $\int x^k H(x) dx$

Order of kernel: A kernel is of k th order if the first non-zero moment is the k th

- Non-negative kernel: order is at most 2

Bias: bias = $O\{(\text{bandwidth})^k\}$

Variance:

variance = $O\left(\frac{1}{n \times \text{bandwidth}}\right)$

and

optimal RMSE = $O(n^{-k/(2k+1)})$

2nd order-penalty gives 4th order kernel (in interior)

Now let $m = 2$ (2nd order difference penalty)

• Assume:

- $K \sim Cn^\gamma$ with $C > 0$ and $\gamma > 4/9$
- $\lambda \sim 4C^4h^4n^{4\gamma-4/9} \sim 4(Khn^{-1/9})^4$.

Then for any $x \in (0, 1)$, when $n \rightarrow \infty$, we have

$$n^{4/9}\{\widehat{f}_n(x) - f(x)\} \Rightarrow N\{\mathcal{B}_1(x), \mathcal{V}_1(x)\},$$

where

- $\mathcal{B}_1(x) = (1/24)h^4f^{(4)}(x) \int x^4 T(x) dx$
- $\mathcal{V}_1(x) = h^{-1} \left\{ \int T^2(x) dx \right\} \sigma^2(x)$
 - $T(x)$ is a fourth order kernel

Mathematical approach

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Conclusions

Main technical device uses roots of the polynomial

$$w(\xi) = \lambda(1 - 4\xi + 6\xi^2 - 4\xi^3 + \xi^4) + \xi^2 = \lambda(1 - \xi)^4 + \xi^2, \quad \lambda > 0$$

- No real roots and no roots of modulus one
- Roots are: r , $\text{conj}(r)$, r^{-1} , $\text{conj}(r)^{-1}$ (all distinct)
- Use the conjugate pair with modulus less than one

Asymptotic Kernel

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Conclusions

- The asymptotic kernel is a linear combination of

$$\exp(-|x|) \cos(x) \quad \text{and} \quad \exp(-|x|) \sin(|x|)$$

- Same equivalent kernel as for smoothing splines with a penalty on the second derivative

Finite-sample kernels, second-order penalty

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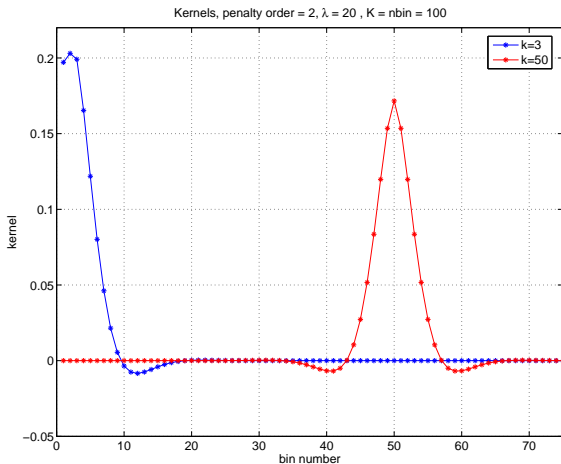
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Linear splines need less knots

Assume $m = 1$ (1st-order difference penalty).

- If $p = 1$ (linear), then require

$$K \sim Cn^\gamma \text{ with } C > 0 \text{ and } \gamma > 1/5$$

- When p was 0 (piecewise constant), we required

$$\gamma > 2/5$$

- Otherwise, results are the same as for 0-degree and linear splines

A similar result holds for $m = 2$.

Conjectures

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Conclusions

- **Conjecture:** For x in the interior:

P-spline \sim N-W estimator with an $2m$ -order kernel

- Recall: m is order of difference penalty
- Kernel order independent of $p =$ degree of spline
- Shown to hold for $m = 1, 2$ and $p = 0, 1$
- $p = 1$ requires less knots than $p = 0$
 - What happens for $p > 1$?
 - **Conjecture:** Still less knots are needed

Unequally spaced X

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Conclusions

- Assume $G(x_t) = t/n$ for a smooth G with $g = G'$
- Fit a spline to (Y_t, u_t) with regression function $f \circ G^{-1}$
 - evaluate this estimate at $G(x)$ to estimate $f(x)$
- Equally spaced knots for (Y_t, u_t) implies knots at sample quantiles for (Y_t, x_t)
- asymptotic bias is

$$h^2(f \circ G^{-1})^{(2)}\{G(x)\} = \frac{h^2}{g^2(x)} \left\{ f^{(2)}(x) - \frac{f'(x)g'(x)}{g(x)} \right\}$$

- Nadaraya-Watson bias is

$$h^2 \left\{ f^{(2)}(x) + \frac{2f'(x)g'(x)}{g(x)} \right\}$$

Additive Models

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Conclusions

Talk by Yingxing Li on bivariate additive model:

- Session 543
- Thursday morning

We use only one of two potential smoothing parameters

Both K and λ are potential smoothing parameters

- In **our** asymptotic theory, **only** λ plays the role of a smoothing parameter
- Could develop a theory where only K plays this role
 - would be similar to regression spline ($\lambda = 0$) theory
- One could also choose K and λ so that both have a non-negligible effect
- **Our theory mimics actual practice**

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Conclusions

- P-spline estimators \approx binned N-W kernel estimators
- The number of knots unimportant if above a minimum
- Degree of spline
 - determines minimum convergence rate for number of knots
 - does not affect rate of convergence
- Order of penalty determines
 - order of equivalent kernel
 - convergence rate of estimator
- m th order penalty \Leftrightarrow smoothing spline with penalty on m th difference

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Thanks for coming